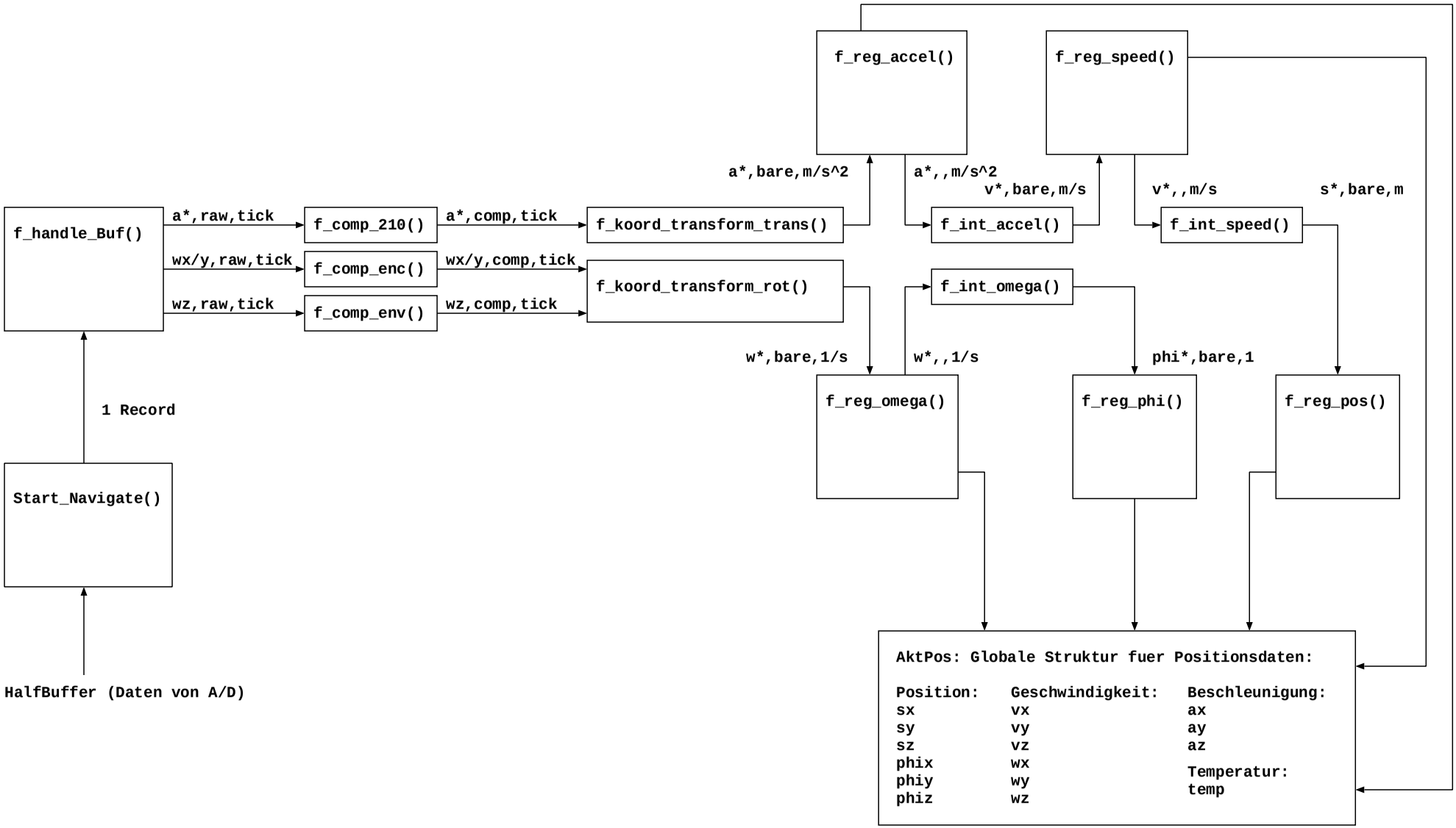
f_handle_Buf()
a*,raw,tick
wx/y,raw,tick
wz,raw,tick
f_comp_210()
f_comp_enc()
f_comp_env()
a*,comp,tick
wx/y,comp,tick
wz,comp,tick
f_koord_transform_trans()
f_koord_transform_rot()
f_reg_accel()
f_reg_speed()
a*,bare,m/s^2
a*,,m/s^2
v*,bare,m/s
v*,,m/s
s*,bare,m
f_int_accel()
f_int_speed()
f_int_omega()
w*,bare,1/s
w*,,1/s
phi*,bare,1
f_reg_omega()
f_reg_phi()
f_reg_pos()
1 Record
Start_Navigate()
HalfBuffer (Daten von A/D)
AktPos: Globale Struktur fuer Positionsdaten:
Position:
sx
sy
sz
phix
phiy
phiz
Geschwindigkeit:
vx
vy
vz
wx
wy
wz
Beschleunigung:
ax
ay
az
Temperatur:
temp